

## 1 Functional description

The digital output module XI221116 is used to output binary 24 V GND control signals in a ctrlX I/O station. The module has 16 channels in a 1-wire technique. The signal state is shown at the channel LED on the removable peripheral connector. The peripheral GND supplies the digital outputs. The logic and peripheral supply as well as the Ethercat-based module communication are routed through the module.



<sup>i</sup> For an application manual of the ctrlX I/O modules, refer to the media directory [www.boschrexroth.com/mediadirectory](http://www.boschrexroth.com/mediadirectory) and enter the search term "R911423458".

<sup>i</sup> Ensure that the current documentation is consulted. For the current documentations, go to [www.boschrexroth.com/mediadirectory](http://www.boschrexroth.com/mediadirectory) and enter the module type as search term.

<sup>i</sup> For the integration into the parent system, the respective ESI files are available. For the ESI files, go to <http://www.boschrexroth.com/electrics>, search term "ESI-Files".

## 2 Ordering data

| Type     | Part number | Description  |
|----------|-------------|--|
| XI221116 | R912009223  | 16-channel digital output module NPN (24 VDC, 0.5 A), 1-wire |

<sup>i</sup> For more ordering data (accessories), go to the product catalog under [www.boschrexroth.com/electrics](http://www.boschrexroth.com/electrics).

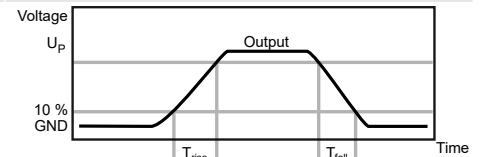
## 3 Technical data

### 3.1 General technical data

|                           |                   |
|---------------------------|-------------------|
| Number of outputs         | 16                |
| Connection method         | Push-in terminal  |
| Connection technique      | 1-wire technique  |
| Output current max.       | 0.5 A per channel |
| Total current of channels | 4 A max.          |

Nominal load Ohmic, 12 W max. (48 Ω; at nominal voltage)

Minimum load 10 kΩ



Rising time ( $T_{Rise}$ ) Without load: 432 μs on the digital input  
10.2 μs at 240 Ω, 100 mA  
Ohmic nominal load: 1.06 μs at 48 Ω, 500 mA

Fall time ( $T_{FALL}$ ) Without load: 0.19 μs on the digital input  
0.2 μs at 240 Ω, 100 mA  
Ohmic nominal load: 0.2 μs at 48 Ω, 500 mA

Inductive switch-off energy 200 mJ max.

Overload response Granular switch-off with automatic restart

Feedback voltage resistance Not resistant to feedback, external measures required

Nominal voltage ( $U_L/U_P$ ) DC 24 V (19.2 V to 30 V, including tolerance and residual ripple) PELV/SELV (safety extra-low voltage)

Current consumption  $U_L$  32 mA

Current consumption  $U_P$  24 mA + load

Max. power consumption of the module 2.04 W

Bit width in the process image 2 bytes (16 bits)

Configuration No address or configuration setting required

Dimensions 12 mm × 105 mm × 99 mm (Width × height × depth)

Weight 100 g (module including connector)

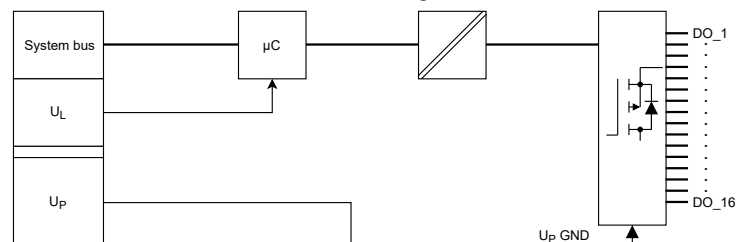
Electrical isolation DC 1211 V  $U_P$  to  $U_L$ , DC 707 V  $U_P/U_L$  to FE (not evaluated by  $U_L$ )

EMC resistance Acc. to EN 61000-6-2 and EN 61000-6-4

Mounting position Vertical, on a horizontal mounting rail

Labeling, approvals CE, UKCA, UL

### 3.2 Internal schematic diagram



### 3.3 Ambient conditions

|                               |               |
|-------------------------------|---------------|
| Ambient temperature ≤ 2,000 m | -25 to +55 °C |
|-------------------------------|---------------|

|  |                               |
|--|-------------------------------|
| 2,000 m to 3,000 m   | -25 to +50 °C                 |
| 3,000 m to 4,000 m   | -25 to +45 °C                 |
| 4,000 m to 5,000 m   | -25 to +40 °C                 |
| Maximum operating altitude<br>Acc. to DIN 60204  | 5,000 m                       |
| Ambient temperature<br>(storage and transport)   | -40 to +70 °C                 |
| Permitted air humidity according<br>to DIN EN 61131-2<br>(Operation, storage, transport) | 10 to 95 %                    |
| Degree of protection<br>Acc. to DIN EN 60 529  | IP20<br>(not evaluated by UL) |
| Protection class<br>Acc. to DIN EN 61010-2-201   | III                           |
| Overvoltage category<br>Acc. to IEC 60664-1  | 2                             |
| Contamination level<br>Acc. to EN 61010-1  | 2, no condensation            |

**NOTICE**

**Defective device due to contaminated air**

- The ambient air must not contain acids, alkaline solutions, corrosive agents, salts, metal vapors and other electrically conductive contaminants in high concentrations.
- The devices to be installed into the housings and installation compartments must at least comply with the degree of protection IP 54 according to DIN EN 60529.
- The device shall be provided in a suitable fire enclosure in the end-use application.

**NOTICE**

**Defective device due to gases jeopardizing functions**

Due to the risk of corrosion, avoid sulphureous gases (e.g. sulphur dioxide (SO<sub>2</sub>) and hydrogen sulphide (H<sub>2</sub>S)). The device is not resistant against these gases.

**NOTICE**

**Defective device due to overheating**

To avoid overheating and to ensure a trouble-free operation of the device, the ambient air has to circulate. Also refer to the section "Installation notes".

### 3.4 Mechanical tests

|  |  |
|--|--|
| Vibration resistance<br>Acc. to DIN EN 60068-2-6 | Oscillations, sinusoidal in all three axes, 5 Hz - 8,4 Hz with 3.5 mm amplitude<br><br>8.4 Hz -150 Hz with 1 g peak acceleration |
| Shock test<br>Acc. to DIN EN 60068-2-27          | Shock stress: Shock resistance in all three axes<br><br>11 ms semi-sinusoidal 15 g   |
| Broadband noise<br>Acc. to DIN EN 60068-2-64     | 20-500 Hz with 1.22 g RMS (Root Mean Square), 30 min in all three axes   |

For the current approvals, go to [www.boschrexroth.com/electrics](http://www.boschrexroth.com/electrics).

## 4 For your safety

### 4.1 Intended use

Use the module only as specified in the data sheet.

### 4.2 User qualification

The product use described in this data sheet is only intended for qualified electricians and staff trained by these qualified electricians. The user has to be familiar with the known safety concepts on automation technology, applicable standards and other guidelines.

## 4.3 Electrical safety

**NOTICE**

**Loss of electric safety**

Unintended handling can affect the device safety! Observe the notes in the present data sheet during installation, commissioning and operation.

## 5 Signal processing

### 5.1 Synchronizing the application

The application is synchronized in the "SM synchronous" mode.

## 6 Process data

### 6.1 Process data of the module

The module is a simple module with a device emulation. Apart from the registers of the EtherCAT slave, no further objects are available for configuration or status.

The following process data is transferred:

| Index (hex) | Object name | Data type | Access | Description      | Default (hex) |
|-------------|-------------|-----------|--------|------------------|---------------|
| 7000:01     | Channel 1   | BOOL      | rw     | Channel 1 Value  | 0             |
| 7010:01     | Channel 2   | BOOL      | rw     | Channel 2 Value  | 0             |
| 7020:01     | Channel 3   | BOOL      | rw     | Channel 3 Value  | 0             |
| 7030:01     | Channel 4   | BOOL      | rw     | Channel 4 Value  | 0             |
| 7040:01     | Channel 5   | BOOL      | rw     | Channel 5 Value  | 0             |
| 7050:01     | Channel 6   | BOOL      | rw     | Channel 6 Value  | 0             |
| 7060:01     | Channel 7   | BOOL      | rw     | Channel 7 Value  | 0             |
| 7070:01     | Channel 8   | BOOL      | rw     | Channel 8 Value  | 0             |
| 7080:01     | Channel 9   | BOOL      | rw     | Channel 9 Value  | 0             |
| 7090:01     | Channel 10  | BOOL      | rw     | Channel 10 Value | 0             |
| 70A0:01     | Channel 11  | BOOL      | rw     | Channel 11 Value | 0             |
| 70B0:01     | Channel 12  | BOOL      | rw     | Channel 12 Value | 0             |
| 70C0:01     | Channel 13  | BOOL      | rw     | Channel 13 Value | 0             |
| 70D0:01     | Channel 14  | BOOL      | rw     | Channel 14 Value | 0             |
| 70E0:01     | Channel 15  | BOOL      | rw     | Channel 15 Value | 0             |
| 70F0:01     | Channel 16  | BOOL      | rw     | Channel 16 Value | 0             |

## 7 Diagnostic strategy

### 7.1 Mechanisms

Different mechanisms are used for the diagnostics of the module.

| Mechanism                  | Diagnostics                                    |
|----------------------------|--|
| EtherCAT state machine     | EtherCAT system diagnostics                    |
| EtherCAT hardware watchdog |  |
| Module status LED          | Shows the general module status                |
| Channel status LED         | Signals the channel status or the error states |

### 7.2 Module status LED

| Device state                                      | LED flashing pattern               |
|---|------------------------------------|
| Booting   | BU BU BU BU BU -- -- -- -- -- ↵    |
| Initialization                                    | BU BU BU BU BU BU BU BU BU BU BU ↵ |
| It is currently configured. Module not yet ready. | GN GN GN GN GN -- -- -- -- -- ↵    |
| Process data transmission, outputs inactive.      | GN GN GN GN GN GN GN GN GN GN -- ↵ |
| Module in "Run" state                             | GN GN GN GN GN GN GN GN GN GN ↵    |
| <b>Error and warning states</b>                   |                                    |
| Logic or peripheral voltage error                 | RD RD RD RD RD RD RD RD RD RD ↵    |
| Communication or configuration error              | RD RD RD RD RD -- -- -- -- -- ↵    |

ⓘ One square corresponds to a period of 200 ms. The arrow represents the end of a cycle.

- LED is not on.
- BU LED is blue.
- GN LED is green.
- RD LED is red.

ⓘ A new status is only displayed after the previous flashing cycle has elapsed. A change in status can thus be delayed up to two seconds.

### 7.3 Channel status LED

Each channel of the module is provided with a channel status LED at the respective signal pin of the plug.

| LED   | Logic signal state |
|-------|--------------------|
| Off   | 0                  |
| Green | 1                  |

## 8 Installation

### 8.1 Clamping point assignment

| Clamping point | Assignment         | Color | Maximum current |
|----------------|--------------------|-------|-----------------|
| 1              | 1 - DO channel 1   | Grey  | 0.5 A           |
| 2              | 2 - DO channel 2   | Grey  | 0.5 A           |
| 3              | 3 - DO channel 3   | Grey  | 0.5 A           |
| 4              | 4 - DO channel 4   | Grey  | 0.5 A           |
| 5              | 5 - DO channel 5   | Grey  | 0.5 A           |
| 6              | 6 - DO channel 6   | Grey  | 0.5 A           |
| 7              | 7 - DO channel 7   | Grey  | 0.5 A           |
| 8              | 8 - DO channel 8   | Grey  | 0.5 A           |
| 9              | 9 - DO channel 9   | Grey  | 0.5 A           |
| 10             | 10 - DO channel 10 | Grey  | 0.5 A           |
| 11             | 11 - DO channel 11 | Grey  | 0.5 A           |
| 12             | 12 - DO channel 12 | Grey  | 0.5 A           |
| 13             | 13 - DO channel 13 | Grey  | 0.5 A           |
| 14             | 14 - DO channel 14 | Grey  | 0.5 A           |
| 15             | 15 - DO channel 15 | Grey  | 0.5 A           |
| 16             | 16 - DO channel 16 | Grey  | 0.5 A           |

Provide the potential reference of the channels via  $U_P$  24 V or use the potential distribution terminal XI822116 (16 × 24 V) with the part number R911406123 or XI824116 (8 × DC 24 V, 8 × GND) with the part number R911406122.

### 8.2 Switching off inductive loads

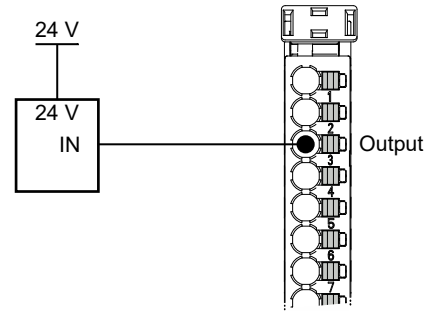
Negative voltages are generated when inductive loads are switched off. If the switch-off energies are greater than specified in the technical data, these switch-off energies can cause damage to the electronics of the module.

#### NOTICE

##### Electronic damage due to overload

Use a suitable external freewheeling circuit to protect the module from high voltages when switching off inductive loads.

### 8.3 Wiring example



### 8.4 Mounting and installation

The application manual for the ctrlX I/O modules contains notes on installation, mounting and dismounting. For the application description, go to:

- [www.boschrexroth.com/MediaDirectory](http://www.boschrexroth.com/MediaDirectory), Search term: "R911423458" or
- <https://docs.automation.boschrexroth.com/doc/4126711705/ctrlx-i-o-anwendungsbeschreibung/latest/en/>

#### NOTICE

##### Destruction of the device due to non-compliance with the application manual

Follow the mounting instructions in the application manual to ensure a correct mounting and to prevent damage to the device.

## 9 License information

### 9.1 EtherCAT®



The ctrlX I/O modules use EtherCAT® technology. "EtherCAT®" is a registered trademark and patented technology licensed by the Beckhoff Automation GmbH, Germany. EtherCAT is an open, internationally standardized standard and developed further by the "EtherCAT Technology Group" (ETG).

